# Lazy Automata Techniques for WS1S

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TACAS'17

- weak monadic second-order logic of one successor
  - ▶ second-order ⇒ quantification over relations;
  - ▶ monadic ⇒ relations are unary (i.e. sets);
  - weak ⇒ sets are finite;
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- corresponds to finite automata [Büchi'60]
- decidable but NONELEMENTARY
  - constructive proof via translation to finite automata

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- decision procedure: the well-known MONA tool
  - sometimes efficient in practice
  - other times the complexity strikes back (unavoidable in general)
  - we try to push the usability border further!!

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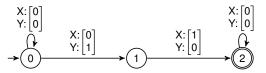
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- Models are represented as a stack of (0-padded) binary strings
- Example:

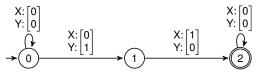
$$\{X \mapsto \emptyset, Y \mapsto \{2,4\}\} \models \varphi \quad \text{iff} \quad {\textstyle X: \begin{bmatrix} 0 \\ Y: \end{bmatrix}} {\textstyle \begin{bmatrix} 0 \\ 0 \end{bmatrix}} {\textstyle \begin{bmatrix} 0 \\ 1 \end{bmatrix}} {\textstyle \begin{bmatrix} 0 \\ 0 \end{bmatrix}} {\textstyle \begin{bmatrix} 0 \\ 1 \end{bmatrix}} \in L(\varphi)$$

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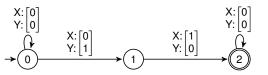
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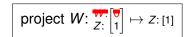


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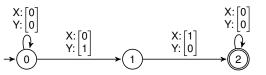
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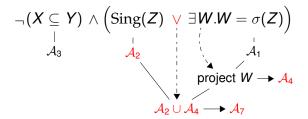
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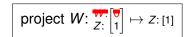
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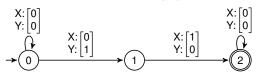
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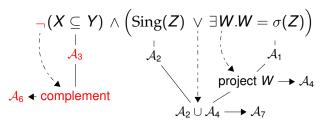




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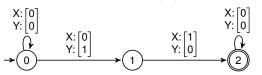


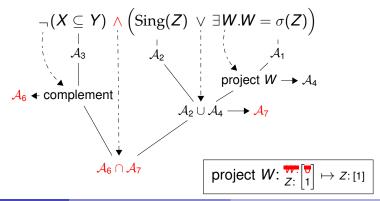
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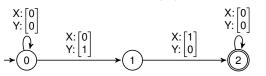
project 
$$W: \frac{W}{Z: \begin{bmatrix} \mathbf{v} \\ 1 \end{bmatrix}} \mapsto Z: [1]$$

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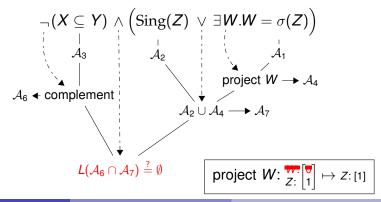




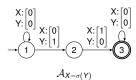
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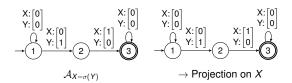
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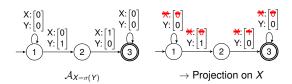
- issue with projection (existential quantification)
  - after removing of the tracks not all models would be accepted (problem with 0-padding)
    - needed for soundness!
    - it is necessary to accept all or none encodings of the models
  - so after projection we need to adjust the final states by saturation
    - pump the final states with all states backward reachable with 0



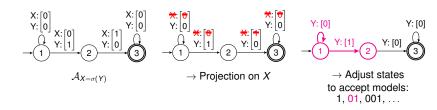
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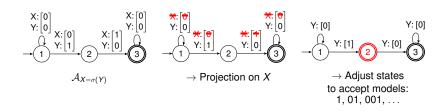
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#### **Ground Formulae**

We focus on validity of ground formulae (all variables are quantified)

■ satisfiability/validity of other formulae: prefixing with ∃/∀

## Key observation for ground formulae

$$\models \varphi \quad \text{iff} \quad \varepsilon \in L(\varphi)$$

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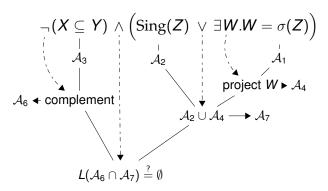
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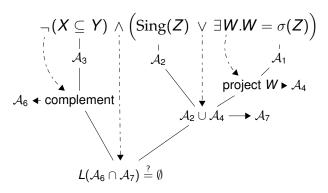
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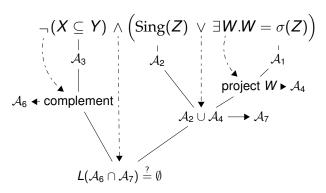
## Why?

- **The Property of Science 19** Formula  $\varphi$  is valid if it accepts everything  $(L(\varphi) = \Sigma^*)$
- Formula  $\varphi$  is unsatisfiable if it accepts nothing ( $L(\varphi) = \emptyset$ )
  - ightharpoonup so it is sufficient to just test membership of arepsilon

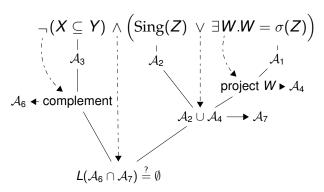




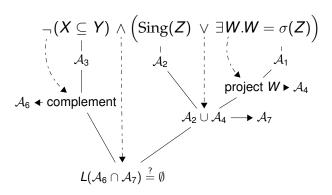
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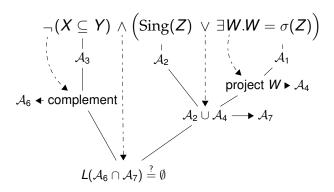


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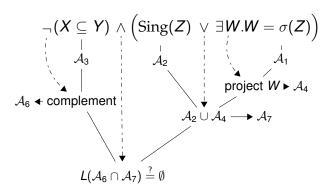


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- **3** For  $A_1 \cap A_2$ , what if  $L(A_1) = \emptyset$ ?
  - ▶ No need to construct  $A_2$  and  $A_1 \cap A_2$ !

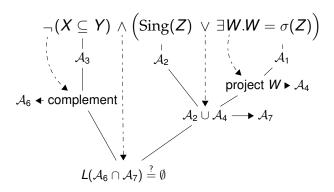




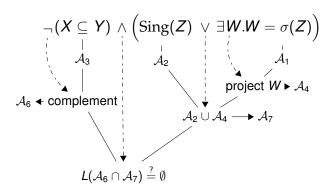
- Instead, we:
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- ▶ Evaluate the  $\varepsilon \in L(A)$  query lazily  $\rightarrow$  on-the-fly
- Compute the saturation fixpoints lazily
- Use subsumption to prune state space

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- **2** Validity checking of ground formula  $\varphi$  is reduced to the  $\varepsilon$ -membership test on  $t_{\varphi}$ 
  - ▶ Intuition: Automaton either accepts  $\Sigma^*$  or nothing, so  $\varepsilon$  test suffices
  - $\blacktriangleright \models \varphi \iff \varepsilon \in t_{\varphi}$

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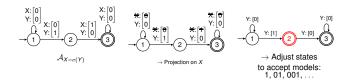
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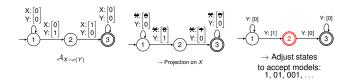
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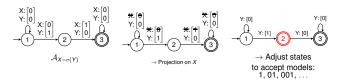
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    - lazy evaluation  $\sim$  iteratively test  $\varepsilon \in t, \varepsilon \in t \overline{0}, \dots$
    - ... until fixpoint reached or satisfying member found



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  - $\triangleright \varepsilon \in t \overline{0}^* \Leftrightarrow \varepsilon \in t \vee \varepsilon \in t \overline{0} \vee \varepsilon \in t \overline{0} \overline{0} \vee \dots$ 
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- 4 Further optimizations
  - e.g. subsumption, continuations, formula preprocessing, etc.



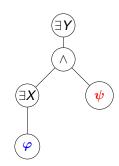
- We represent the formula symbolically as a language terms  $t_{\exists Y.(\exists X.\varphi) \land \psi}$  and test the emptiness.
- $\varepsilon \in t_{\exists Y.(\exists X.\varphi) \land \psi} \iff \varepsilon \in t_{\exists X.\varphi} \cap t_{\psi} \bar{0}^*$   $\iff \varepsilon \in t_{\exists X.\varphi} \cap t_{\psi} \lor \varepsilon \in t_{\exists X.\varphi} \cap t_{\psi} \bar{0} \lor \varepsilon \in t_{\exists X.\varphi} \cap t_{\psi} \bar{0}^2 \dots$
- We will demonstrate our method just on testing if  $\varepsilon \in t_{\exists X._{\varphi}} \cap t_{\psi}$ 
  - (some details will be omitted)

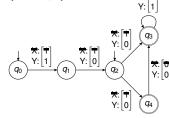
# Validity checking of $\exists Y. (\exists X. \varphi) \land \psi$ $\downarrow^{X: [1]} \downarrow^{X: [1]} \downarrow^{X: [1]} \downarrow^{X: [1]} \downarrow^{X: [1]} \downarrow^{X: [0]} \downarrow$

Term  $t_{\exists X, \varphi}$  corresponds to the left subformula  $\exists X. \varphi$ 

# 

Term  $t_{\exists X, \varphi}$  corresponds to the left subformula  $\exists X. \varphi$ 

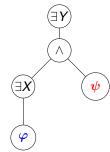


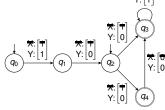


(a) Automaton for  $\exists X.\varphi$ 

$$X:\begin{bmatrix}1\\Y:\begin{bmatrix}0\\0\end{bmatrix}Y:\begin{bmatrix}0\\0\end{bmatrix} \\ Y:\begin{bmatrix}0\\0\end{bmatrix} \\ Y:\begin{bmatrix}0\\1\end{bmatrix} \\ Y:\begin{bmatrix}1\\1\end{bmatrix} \\ Y:\begin{bmatrix}1\\1\\1\end{bmatrix} \\$$

- Term  $t_{\exists X.\varphi}$  corresponds to the left subformula  $\exists X.\varphi$
- Term  $t_{\psi}$  corresponds to the right subformula  $\psi$





(a) Automaton for  $\exists X.\varphi$ 



(b) Automaton for *ψ* 

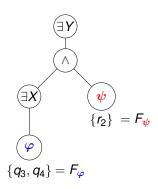
- We commence the emptiness check from final states of leaf automata.
- (After projection new final states are backward reachable from current final states)

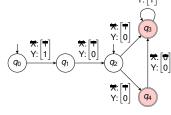
# Validity checking of $\exists Y.(\exists X.\varphi) \land \psi$ (a) Automaton for $\exists X.\varphi$

(b) Automaton for  $\psi$ 

 $\begin{array}{c}
X : \begin{bmatrix} 1 \\ Y : \begin{bmatrix} 1 \end{bmatrix} X : \begin{bmatrix} 0 \\ 1 \end{bmatrix} \\
Y : \begin{bmatrix} 1 \end{bmatrix}
\end{array}$ 

- We commence the emptiness check from final states of leaf automata.
- (After projection new final states are backward reachable from current final states)

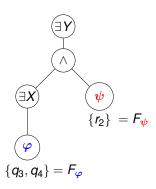


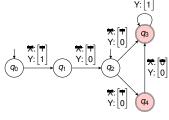


(a) Automaton for  $\exists X.\varphi$ 



- We commence the emptiness check from final states of leaf automata.
- (After projection new final states are backward reachable from current final states)

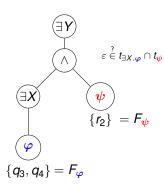


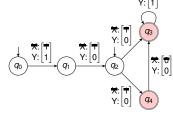


(a) Automaton for  $\exists X.\varphi$ 

(b) Automaton for  $\psi$ 

 $\mathbf{\epsilon} \in t_{\exists X.\boldsymbol{\varphi}} \cap t_{\boldsymbol{\psi}} \iff$ 



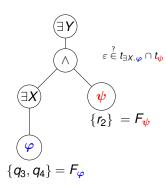


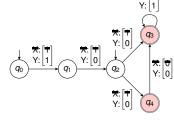
(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c} X:\begin{bmatrix}1\\Y:\begin{bmatrix}0\end{bmatrix}X:\begin{bmatrix}0\\Y:\begin{bmatrix}0\end{bmatrix}\end{bmatrix}\\Y:\begin{bmatrix}0\end{bmatrix}\end{array}$$

$$\begin{array}{c} Y:\begin{bmatrix}1\\Y:\begin{bmatrix}1\end{bmatrix}X:\begin{bmatrix}0\\Y:\begin{bmatrix}1\end{bmatrix}\end{bmatrix}\\Y:\begin{bmatrix}1\end{bmatrix}\end{array}$$





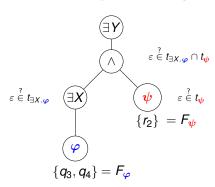


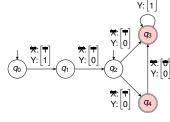
(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c}
X : \begin{bmatrix} 1 \\ Y : \begin{bmatrix} 0 \end{bmatrix} X : \begin{bmatrix} 0 \\ Y : \begin{bmatrix} 0 \end{bmatrix} Y : \begin{bmatrix} 0 \end{bmatrix} \\
\end{array}$$

$$\begin{array}{c}
X : \begin{bmatrix} 1 \\ Y : \end{bmatrix} X : \begin{bmatrix} 0 \end{bmatrix} \\
Y : \begin{bmatrix} 1 \end{bmatrix} Y : \begin{bmatrix} 1 \end{bmatrix} Y : \begin{bmatrix} 1 \end{bmatrix}$$

$$\varepsilon \in t_{\exists X.\varphi} \cap t_{\psi} \iff \\ \Longleftrightarrow \varepsilon \in t_{\exists X.\varphi} \wedge \varepsilon \in t_{\psi}$$

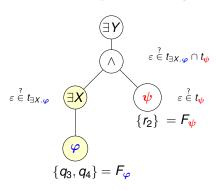


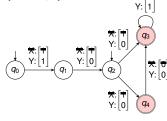


(a) Automaton for  $\exists X.\varphi$ 



$$\varepsilon \in t_{\exists X.\varphi} \cap t_{\psi} \iff \\ \Longleftrightarrow \varepsilon \in t_{\exists X.\varphi} \wedge \varepsilon \in t_{\psi}$$





(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c} X : \begin{bmatrix} 1 \\ Y : \begin{bmatrix} 0 \end{bmatrix} X : \begin{bmatrix} 0 \\ Y : \begin{bmatrix} 0 \end{bmatrix} Y : \begin{bmatrix} 0 \end{bmatrix} \\ Y : \begin{bmatrix} 0 \end{bmatrix} Y : \begin{bmatrix} 0 \end{bmatrix} \end{array}$$

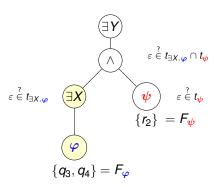
$$\begin{array}{c} X : \begin{bmatrix} 1 \\ Y : \begin{bmatrix} 1 \end{bmatrix} X : \begin{bmatrix} 0 \\ Y : \begin{bmatrix} 1 \end{bmatrix} Y : \begin{bmatrix} 1 \end{bmatrix} \\ Y : \begin{bmatrix} 1 \end{bmatrix} Y : \begin{bmatrix} 1 \end{bmatrix} \end{array}$$

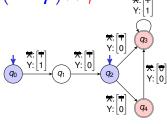
(b) Automaton for  $\psi$ 

$$\varepsilon \in t_{\exists X.\varphi} \iff \varepsilon \in t_{\varphi} - \bar{0}^*$$

$$\iff \varepsilon \in t_{\varphi} \lor \varepsilon \in t_{\varphi} - \bar{0} \lor \varepsilon \in t_{\varphi} - \bar{0}^2 \dots$$

 $\bullet \quad \varepsilon \in t_{\varphi} \iff I_{\varphi} \cap F_{\varphi} \neq \emptyset.$ 

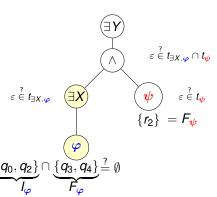


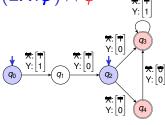


(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{cccc}
X : \begin{bmatrix} 1 \\ X : \begin{bmatrix} 0 \end{bmatrix} & X : \begin{bmatrix} 0 \\ Y : \begin{bmatrix} 0 \end{bmatrix} & Y : \begin{bmatrix} 0 \end{bmatrix} &$$

- $\varepsilon \in t_{\exists X.\varphi} \iff \varepsilon \in t_{\varphi} \bar{0}^*$   $\iff \varepsilon \in t_{\varphi} \lor \varepsilon \in t_{\varphi} \bar{0} \lor \varepsilon \in t_{\varphi} \bar{0}^2 \dots$
- $\bullet \quad \varepsilon \in t_{\varphi} \iff I_{\varphi} \cap F_{\varphi} \neq \emptyset.$





(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c}
X : \begin{bmatrix} 1 \\ X : \end{bmatrix} X : \begin{bmatrix} 0 \\ Y : \end{bmatrix} C_1 \\
Y : \begin{bmatrix} 0 \\ Y : \end{bmatrix} Y : \begin{bmatrix} 0 \\ Y : \end{bmatrix} C_2
\end{array}$$

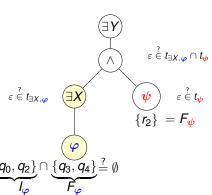
$$\begin{array}{c}
X : \begin{bmatrix} 1 \\ Y : \end{bmatrix} X : \begin{bmatrix} 0 \\ Y : \end{bmatrix} C_2$$

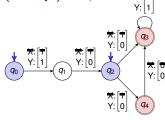
(b) Automaton for  $\psi$ 

$$\varepsilon \in t_{\exists X.\varphi} \iff \varepsilon \in t_{\varphi} - \bar{0}^*$$

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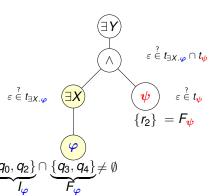


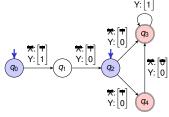


(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c}
X : \begin{bmatrix} 1 \\ X : \end{bmatrix} X : \begin{bmatrix} 0 \\ Y : \end{bmatrix} & (f_1) \\
Y : \begin{bmatrix} 0 \\ Y : \end{bmatrix} & (f_2) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix} & (f_3) & (f_3) & (f_3) & (f_3) & (f_3) & (f_3) \\
Y : \end{bmatrix} & (f_3) \\
Y : \end{bmatrix} & (f_3) \\
Y : \end{bmatrix} & (f_3) \\
Y : \end{bmatrix} & (f_3) \\
Y : \end{bmatrix} & (f_3) \\
Y : \end{bmatrix} & (f_3) &$$

- ... but we cannot conclude that  $\varepsilon \notin t_{\exists X.\varphi}$ , ...



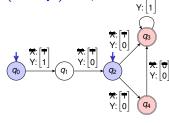


(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c}
X : \begin{bmatrix} 1 \\ X : \begin{bmatrix} 0 \end{bmatrix} \\ Y : \begin{bmatrix} 1 \\ Y : \end{bmatrix}$$

- ... but we cannot conclude that  $\varepsilon \notin t_{\exists X.\varphi}$ , ...

### Validity checking of $\exists Y.(\exists X.\varphi) \land \psi$ $\varepsilon \stackrel{?}{\in} t_{\exists X.\varphi} \cap t_{\psi}$ $\varepsilon \stackrel{?}{\in} t_{\exists X.\varphi}$ $\varepsilon \stackrel{?}{\in} t_{\pmb{\psi}}$

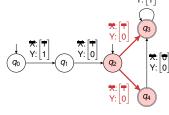


(a) Automaton for  $\exists X.\varphi$ 



- We have to saturate the final states (because of projection)
- One step of saturation yields set of states  $F_{\omega} \overline{0}$ .

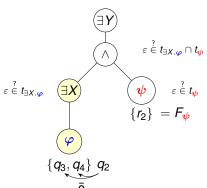
### Validity checking of $\exists Y.(\exists X.\varphi) \land \psi$ $\varepsilon \stackrel{?}{\in} t_{\exists X.\varphi} \cap t_{\psi}$ $\varepsilon \stackrel{?}{\in} t_{\exists X.\varphi}$ $\varepsilon \stackrel{?}{\in} t_{\pmb{\psi}}$

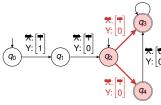


(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c}
X : \begin{bmatrix} 1 \\ X : \begin{bmatrix} 0 \end{bmatrix} \\ Y : \begin{bmatrix} 0 \end{bmatrix} \\$$

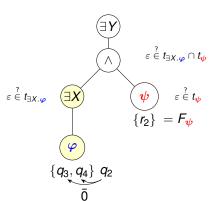
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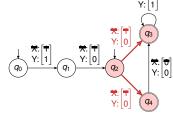




(a) Automaton for  $\exists X.\varphi$ 

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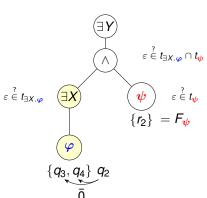


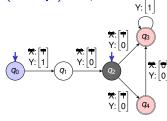


(a) Automaton for  $\exists X.\varphi$ 



• We repeat the check: 
$$\varepsilon \in t_{\varphi} - \overline{0} \iff t_{\varphi} \cap F_{\varphi} - \overline{0} \neq \emptyset$$

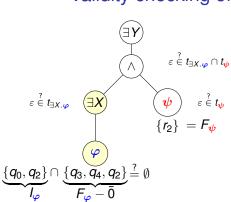


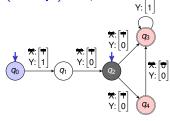


(a) Automaton for  $\exists X.\varphi$ 



■ We repeat the check: 
$$\varepsilon \in t_{\varphi} - \overline{0} \iff I_{\varphi} \cap F_{\varphi} - \overline{0} \neq \emptyset$$

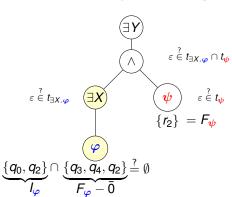


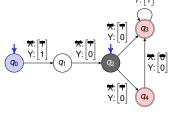


(a) Automaton for  $\exists X.\varphi$ 



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$$\varepsilon \in t_{\varphi} - \overline{0} \iff I_{\varphi} \cap F_{\varphi} - \overline{0} \neq \emptyset$$



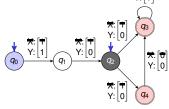


(a) Automaton for  $\exists X.\varphi$ 



- Since  $\{q_0, q_2\} \cap \{q_3, q_4, q_2\} \neq \emptyset, \dots$
- ... we conclude that  $\varepsilon \in t_{\varphi} \overline{0}$  and hence  $\varepsilon \in t_{\exists X.\varphi}$ .

# Validity checking of $\exists Y.(\exists X.\varphi) \land \psi$ $\varepsilon \stackrel{?}{\in} t_{\exists X.\omega} \cap t_{\psi}$ X:[†] Y:[1] $\varepsilon \in t_{X,\varphi}$ $\varepsilon \stackrel{?}{\in} t_{\pmb{\psi}}$



$$\underbrace{\{q_0,q_2\}}_{I_{\varphi}} \cap \underbrace{\{q_3,q_4,q_2\}}_{F_{\varphi}-\bar{0}} \neq \emptyset$$

(a) Automaton for  $\exists X.\varphi$ 

$$\begin{array}{c}
X: \begin{bmatrix} 1 \\ X : \begin{bmatrix} 0 \end{bmatrix} & F_1 \\
Y: \begin{bmatrix} 0 \end{bmatrix} & F_2 \\
\end{array}$$

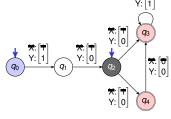
$$\xrightarrow{f_0}$$

$$X: \begin{bmatrix} 1 \\ X : \begin{bmatrix} 0 \end{bmatrix} & F_2 \\
\end{array}$$

$$\xrightarrow{f_0}$$

- Since  $\{q_0, q_2\} \cap \{q_3, q_4, q_2\} \neq \emptyset, \dots$
- ... we conclude that  $\varepsilon \in t_{\varphi} \overline{0}$  and hence  $\varepsilon \in t_{\exists X, \varphi}$ .

# Validity checking of $\exists Y.(\exists X.\varphi) \land \psi$ $\varepsilon \stackrel{?}{\in} t_{\exists X. \varphi} \cap t_{\psi}$ X: [†] Y: [1] $\varepsilon \stackrel{?}{\in} t_{X,\varphi}$ $\varepsilon \stackrel{?}{\in} t_{\pmb{\psi}}$



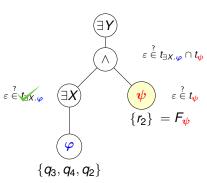
(a) Automaton for  $\exists X.\varphi$ 

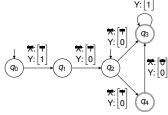


(b) Automaton for  $\psi$ 

- However, we cannot short-circuit the test.
- So we have to compute  $\varepsilon \in t_{\psi}$

 $\{q_3, q_4, q_2\}$ 

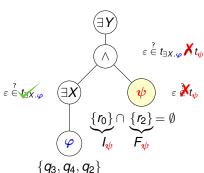


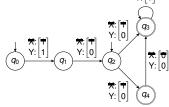


(a) Automaton for  $\exists X.\varphi$ 



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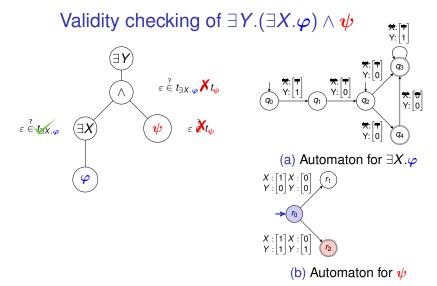




(a) Automaton for  $\exists X.\varphi$ 



- However, we cannot short-circuit the test.
- So we have to compute  $\varepsilon \in t_{\psi}$



Until we find satisfying member or all of the fixpoints are computed...

- lazy evaluation
  - ▶ if one branch of a binary operator suffices: short-circuit!

- if one branch of a binary operator suffices: short-circuit!
- ▶ if we find a satisfying guy in a fixpoint computation: short-circuit!

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- the algorithm has 2 interleaved phases:
  - 1 testing  $\varepsilon$ -membership
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  - 1 testing  $\varepsilon$ -membership
  - 2 computing left quotients
- when computing quotients, we may need the result of a previously short-circuited operation
  - one need to continue unfolding the fixpoint
- combination with the explicit automata procedure (MONA)
  - we can prepare a minimal automaton for a subformula
  - reduces the underlying state space
  - various heuristics
    - we explicitly construct quantifier-free subformulae

#### Subsumption

- when computing fixpoints, some elements can subsume others
- keep fixpoint states minimal (cf. antichains)
- subsumption even on partially computed elements

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#### Formula pre-processing

- pre-processing of the formula can greatly affect performance
- anti-prenexing pushing quantifiers down can reduce the explored state space (even exponentially!)

#### Experimental Evaluation of our tool GASTON

- Results on formulae generated by the UABE tool
  - formulae encode various array invariants
- $lue{}$   $\infty$  represents that the tool timeouted in 2 minutes

Benchmark	Mo	NA	GASTON		
Delicilliark	Time [s]	Space	Time [s]	Space	
a-a	1.51	30 253	$\infty$	$\infty$	
ex10	6.92	131 835	11.82	82 236	
ex11	4.04	2 3 9 3	0.10	4 1 5 6	
ex12	0.11	2 5 9 1	5.40	68 159	
ex13	0.01	2601	0.87	16883	
ex16	0.01	3 384	0.18	3 960	
ex17	3.15	165 173	0.09	3 9 5 2	
ex18	0.18	19 463	$\infty$	$\infty$	
ex2	0.10	26 565	0.01	1 841	
ex20	1.26	1 077	0.21	12 266	
ex21	1.51	30 253	$\infty$	$\infty$	
ex4	0.03	6 797	0.33	22 442	
ex6	3.69	27 903	21.44	132 848	
ex7	0.75	857	0.01	594	
ex8	6.83	106 555	0.01	1 624	
ex9	6.37	586 447	8.31	412417	
fib	0.04	8128	22.15	126 688	

# Experimental Evaluation of our tool GASTON

- Results on set of parametrized benchmarks up to k = 20
- lacksquare oom(k) represents that the tool run out of memory on formula k
- lacksquare  $\infty$ (k) represents that the tool timeouted in 2 minutes on formula k

Benchmark	Mona	DWINA	Toss	COALG	SFA	GASTON
HornLeq	oom(18)	0.03	0.08	∞(08)	0.03	0.01
HornLeq (+3)	oom(18)	∞(11)	0.16	∞(07)	∞(11)	0.01
HornLeq (+4)	oom(18)	∞(13)	0.04	∞(06)	∞(11)	0.01
HornIn	oom(15)	∞(11)	0.07	∞(08)	$\infty$ (08)	0.01
HornTrans	86.43	∞(14)	N/A	N/A	38.56	1.06
SetClosed	oom(05)	∞(14)	$\infty$ (03)	∞(01)	$\infty$ (04)	∞(06)
SetSingle	oom(04)	∞(08)	0.10	N/A	$\infty$ (03)	0.01
Ex8	oom(08)	N/A	N/A	N/A	N/A	0.15
Ex11(10)	oom(14)	N/A	N/A	N/A	N/A	1.62

- DWINA: Fiedor et al.: Nested antichains for WS1S
- Toss: Ganzow and Kaizer: New algorithm for weak monadic second-order login on inductive structures
- COALG: Traytel: A coalgebraic decision procedure for WS1S
- SFA: D'Antoni and Veanes: Minimization of symbolic automata

#### **Future Work**

- extension to WSkS
  - weak monadic second-order logic of k successors
  - opens whole new world of tree structures

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- application of the ideas in other automata-handling algorithms