

Fully Automated Shape Analysis Based on Forest Automata[†]

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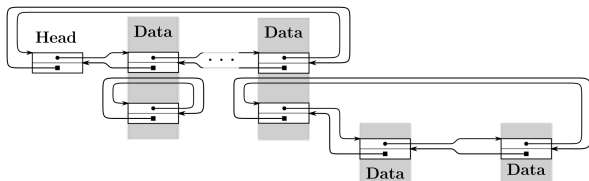
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[†]To appear in *Proc. of CAV'13*.

Shape Analysis

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 - a notoriously difficult problem

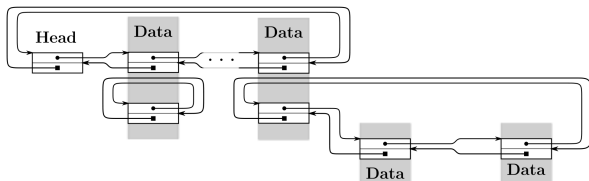


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- ▶ help from the outside (loop invariants, inductive predicates)

■ Classes of errors:

- ▶ **error line** reachability
- ▶ **invalid pointer** dereference
- ▶ occurrence of **garbage**

■ Separation Logic

- 😊 local reasoning, well scalable
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■ Abstract Regular Tree Model Checking (ARTMC)

- ☺ uses tree automata (TA), flexible and refinable abstraction
- ☹ monolithic encoding of the heap, not very scalable

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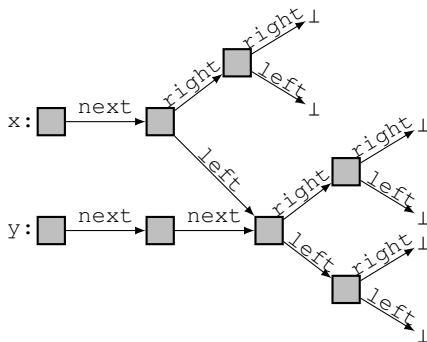
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 - representing sets of heaps using TA

Heap Representation

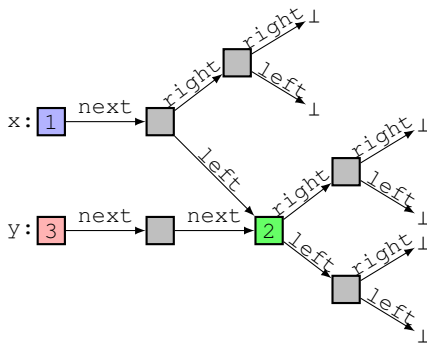
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Heap Representation

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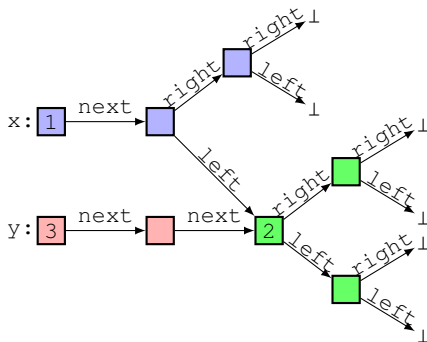
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 - by variables, or
 - multiple times
- Split the heap into **tree components**

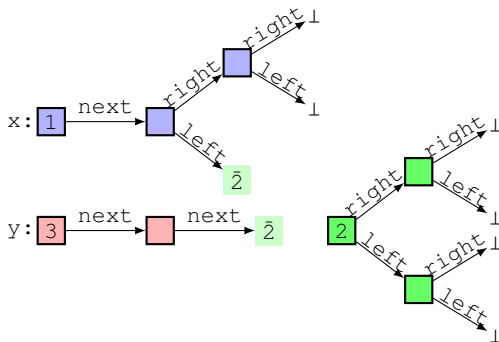


Heap Representation

■ Forest decomposition of a heap

- ▶ Identify **cut-points**
- ▶ Split the heap into **tree components**
- ▶ **References** are explicit

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Heap Representation

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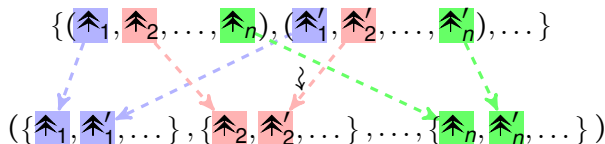
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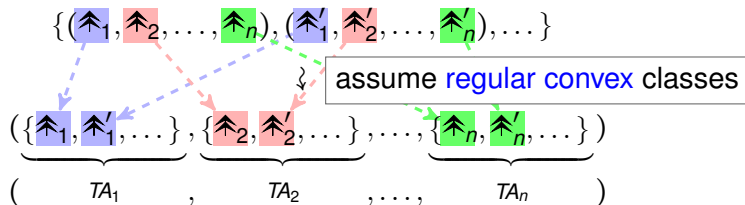
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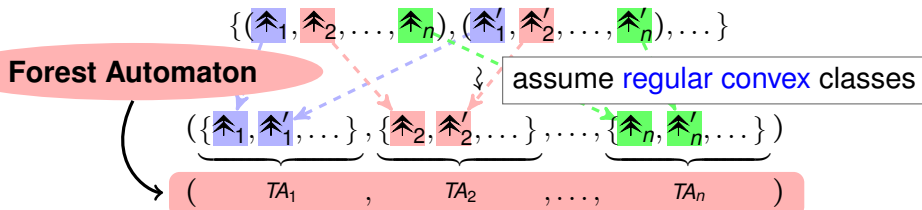
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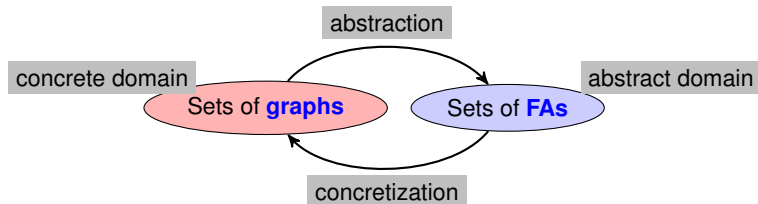
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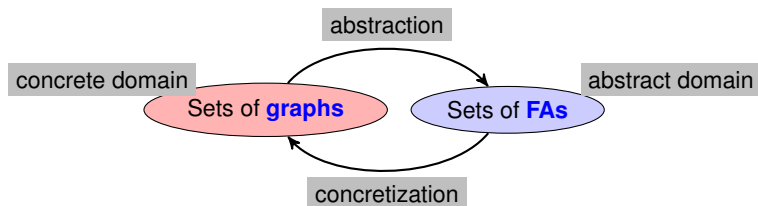
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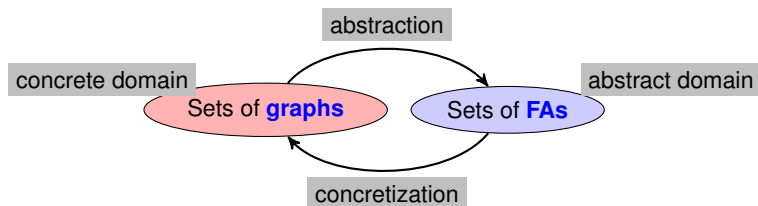


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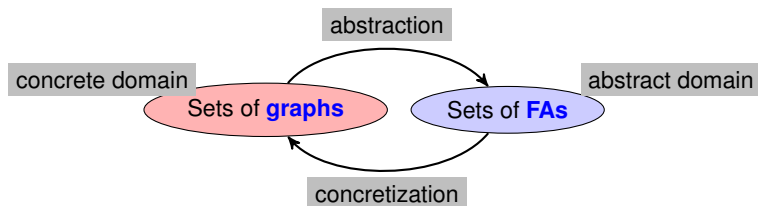
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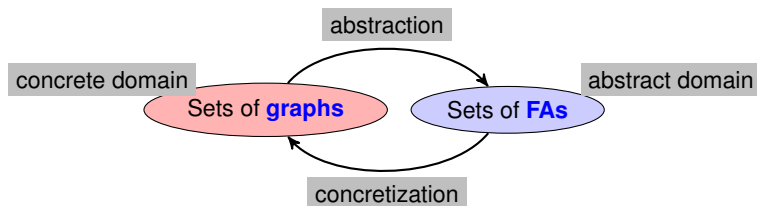
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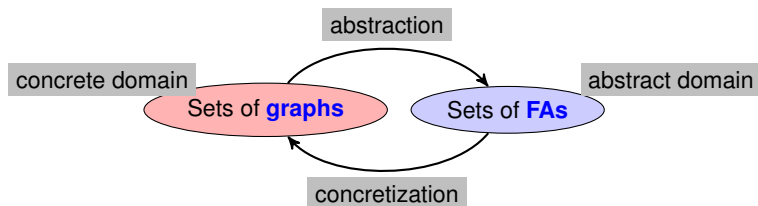
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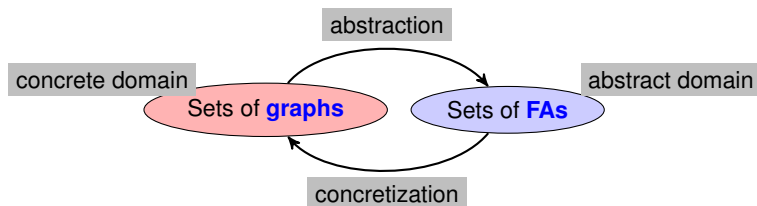
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check symbols on transitions

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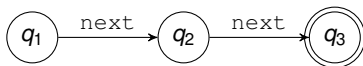
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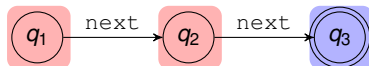
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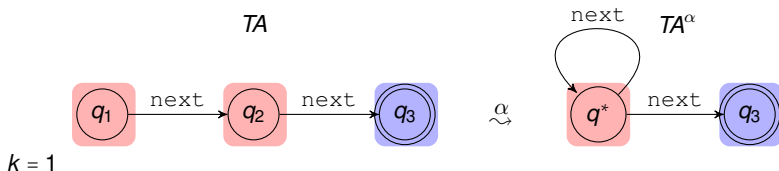
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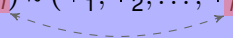
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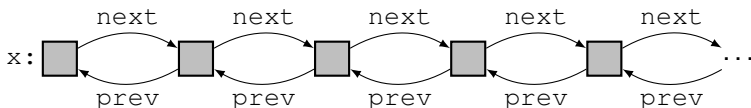
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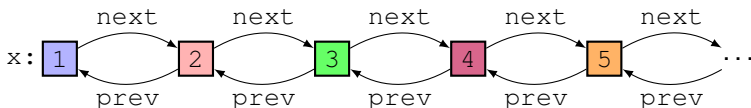


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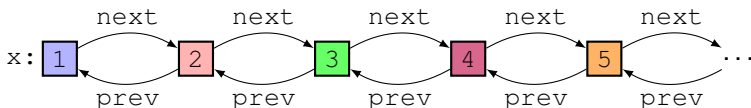


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- doubly linked lists (DLLs), circular lists, nested lists,
- trees with parent pointers,
- skip lists

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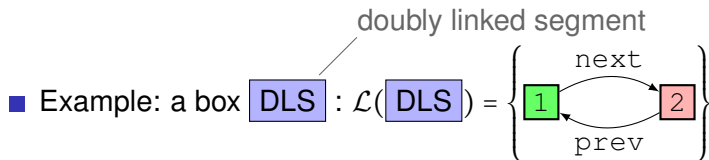
doubly linked segment

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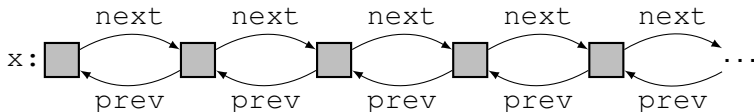
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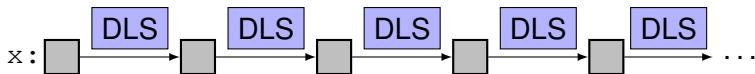
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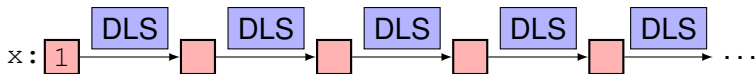
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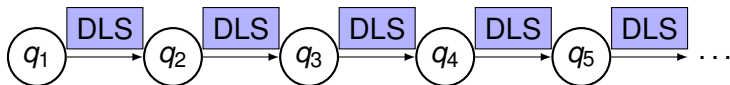
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- Intuition: replace **repeated subgraphs** with a **single symbol**

■ Example: a box **DLS** : $\mathcal{L}(\text{DLS}) = \left\{ \begin{array}{c} \text{next} \\ \text{1} \rightleftarrows \text{2} \\ \text{prev} \end{array} \right\}$

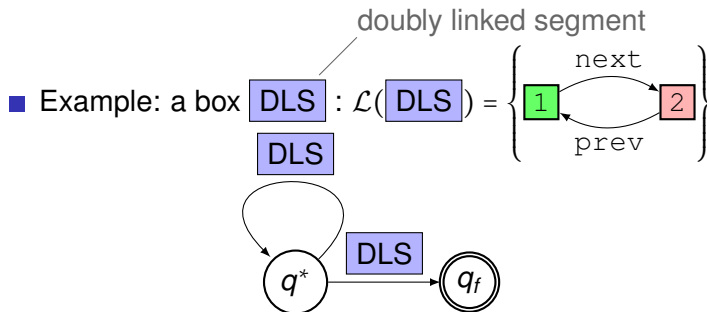
doubly linked segment



Hierarchical Forest Automata

■ Hierarchical Forest Automata

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The Challenge

How to find “the right” boxes?

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- CAV'11 — database of boxes
- CAV'13 — automatic discovery

Learning of Boxes

- compromise between

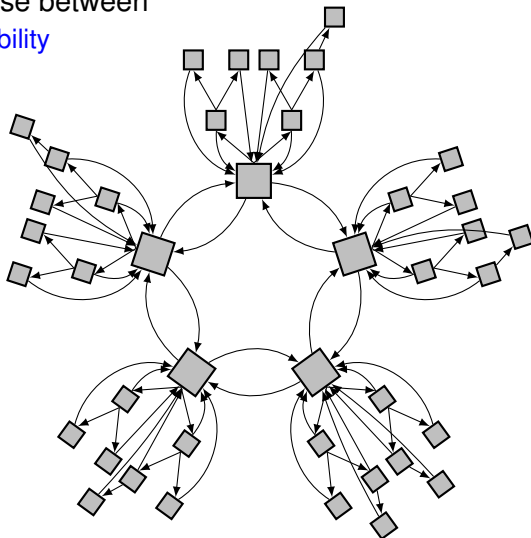
Learning of Boxes

- compromise between
 - [reusability](#)

Learning of Boxes

■ compromise between

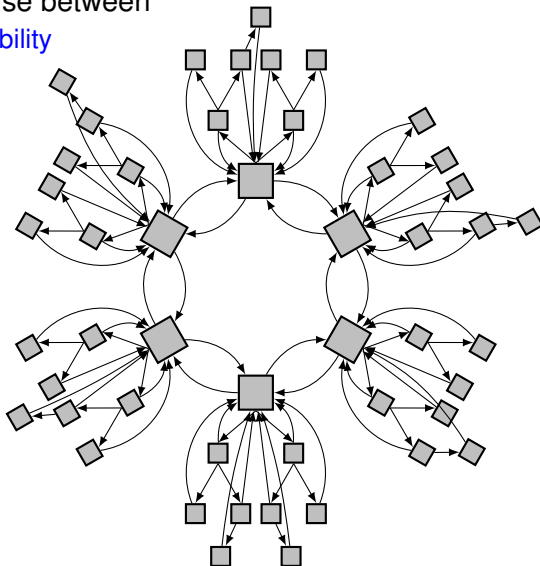
▸ reusability



Learning of Boxes

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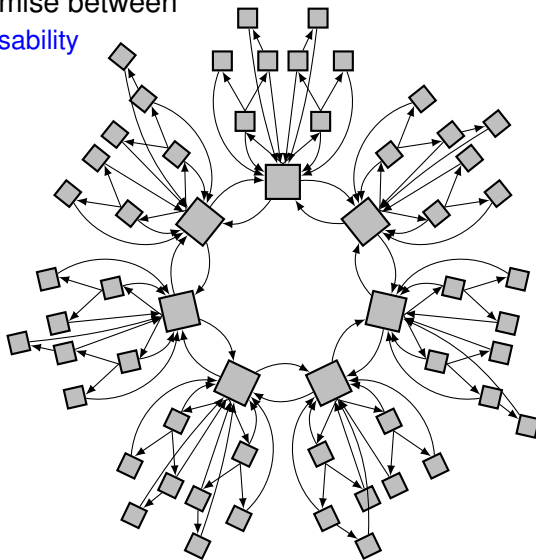
▸ reusability



Learning of Boxes

■ compromise between

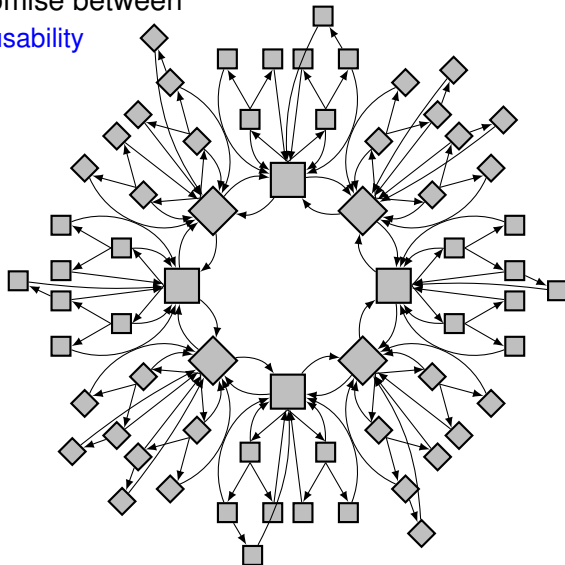
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Learning of Boxes

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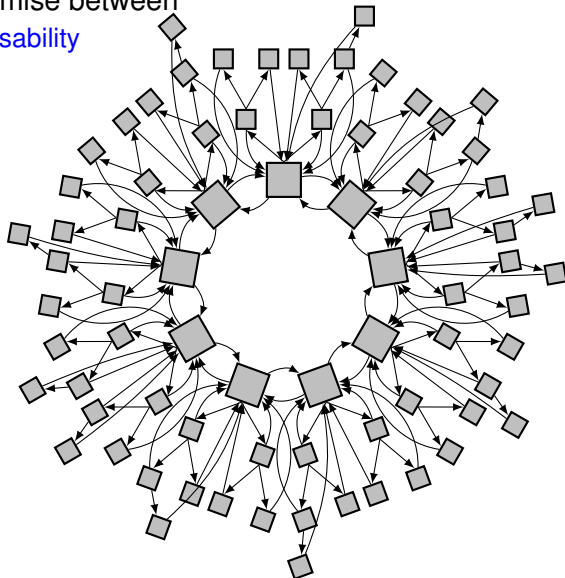
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Learning of Boxes

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Learning of Boxes

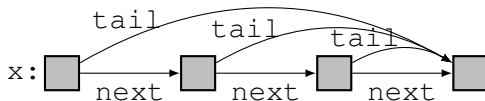
- compromise between
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Learning of Boxes

- compromise between
 - reusability
 - ability to hide cut-points

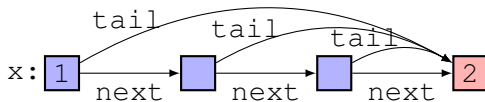
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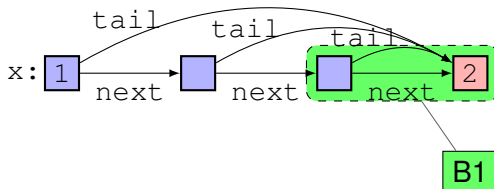
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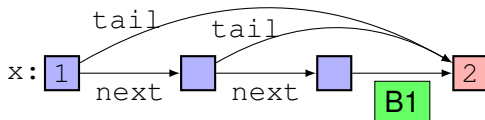
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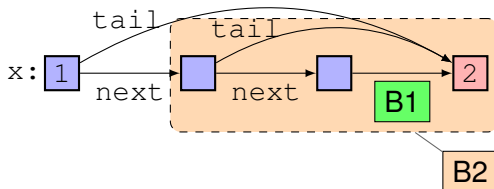
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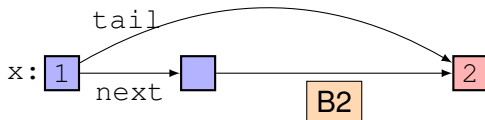
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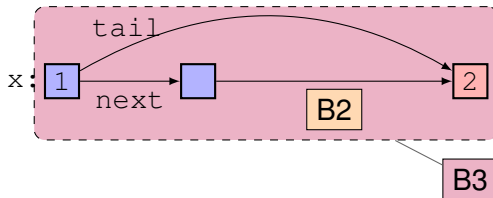
Learning of Boxes

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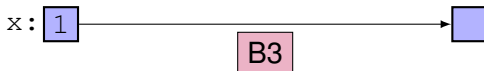
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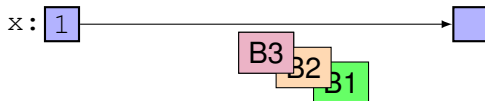
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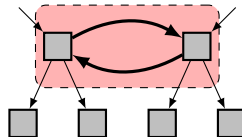
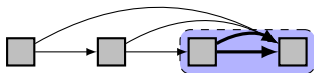
Learning of Boxes: Knots

Knots

Learning of Boxes: Knots

Knots

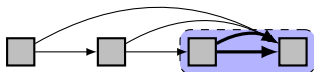
- 1 smallest subgraphs meaningful to be folded:



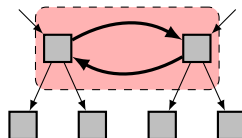
Learning of Boxes: Knots

Knots

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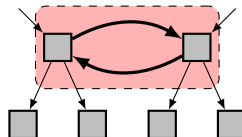
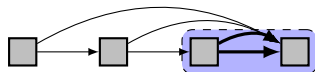
- 2 handle inputs/outputs



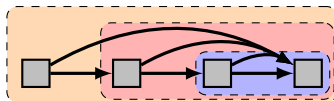
Learning of Boxes: Knots

Knots

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- 2 handle inputs/outputs
 - join intersecting knots



Learning of Boxes: Knots

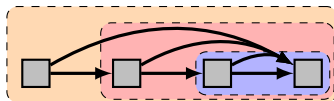
Knots

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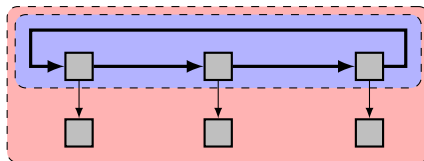


- 2 handle inputs/outputs

- ▶ **join** intersecting knots

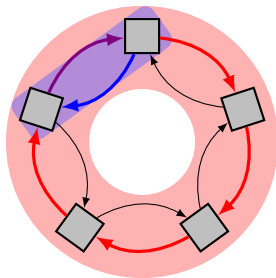


- ▶ **enclose** paths from inner nodes to leaves

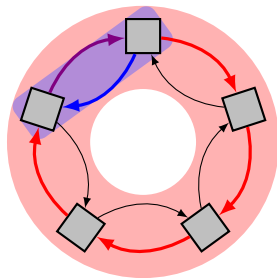


3 complexity

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- find basic knots with $1, 2, \dots$ cut-points

Widening Revisited

- learning and folding of boxes in the abstraction loop

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Fold boxes that will, after abstraction, appear on cycles of automata.

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1 **Algorithm:** Abstraction Loop

2 *Unfold solo boxes*

3 **repeat**

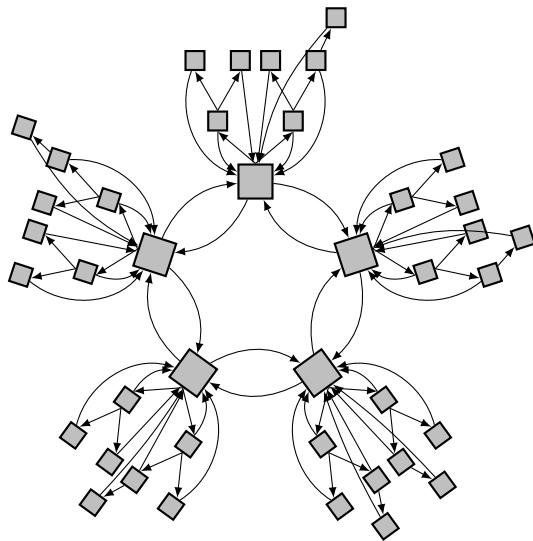
4 *Abstract*

5 *Fold*

6 **until** fixpoint

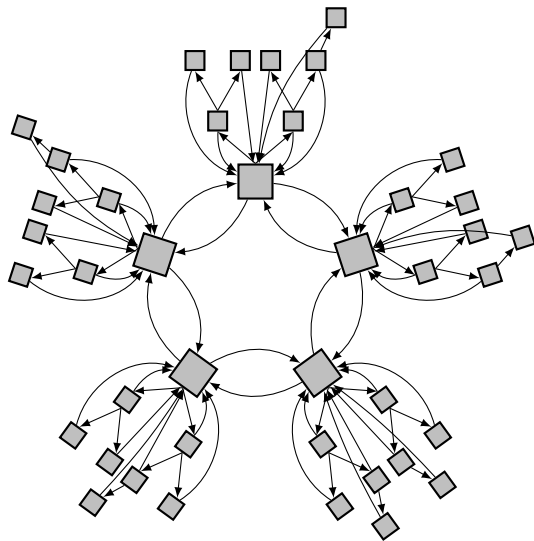
not on a cycle

Learning of Boxes: Example



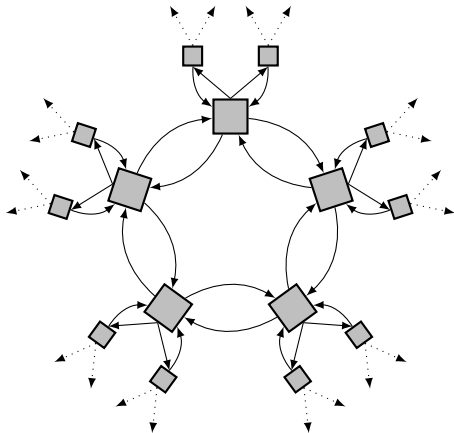
- 1 *Unfold solo boxes*
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Learning of Boxes: Example



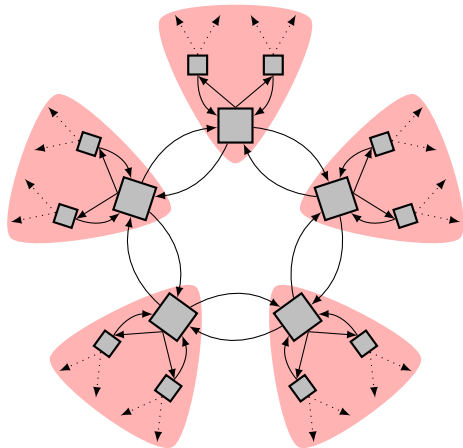
- 1 **Unfold solo boxes**
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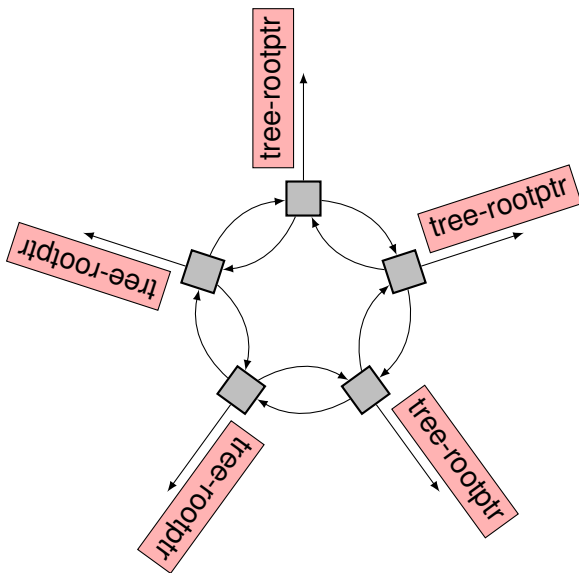
- 1 *Unfold solo boxes*
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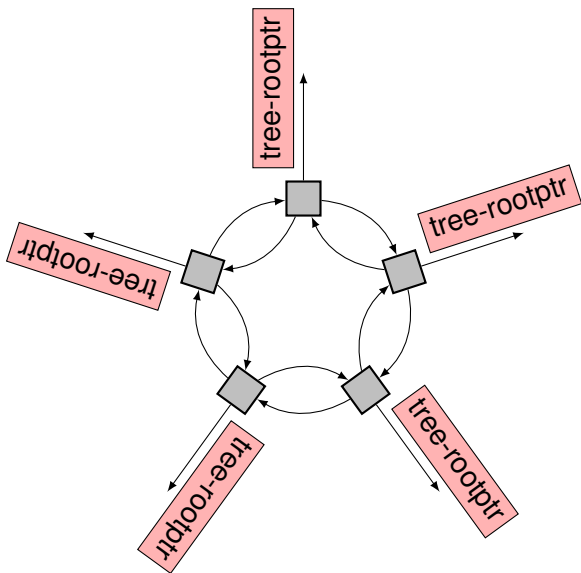
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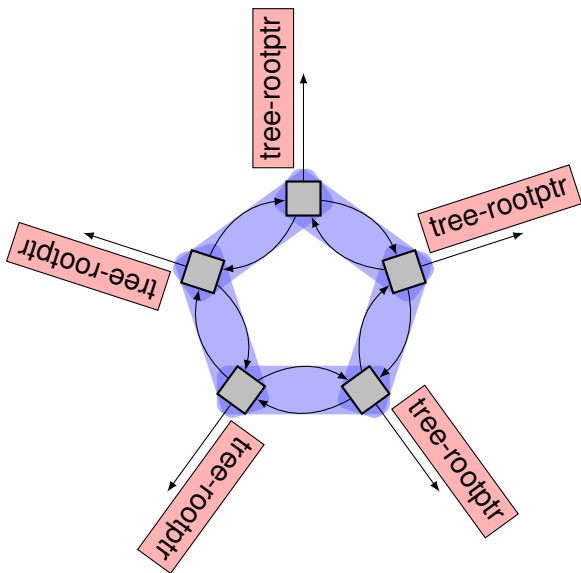
- 1 *Unfold solo boxes*
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Learning of Boxes: Example



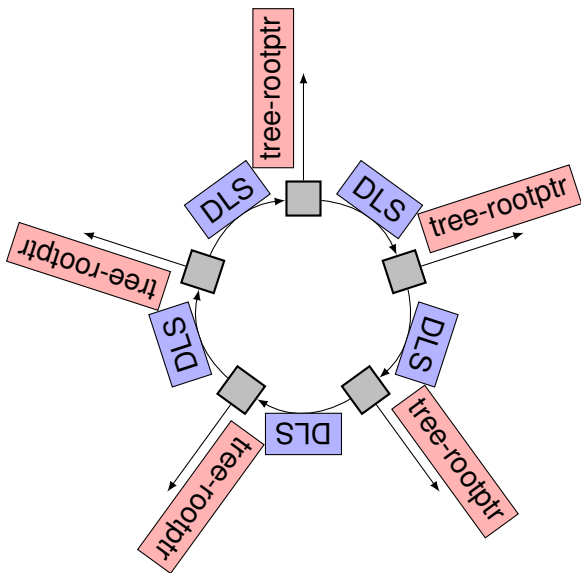
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Learning of Boxes: Example



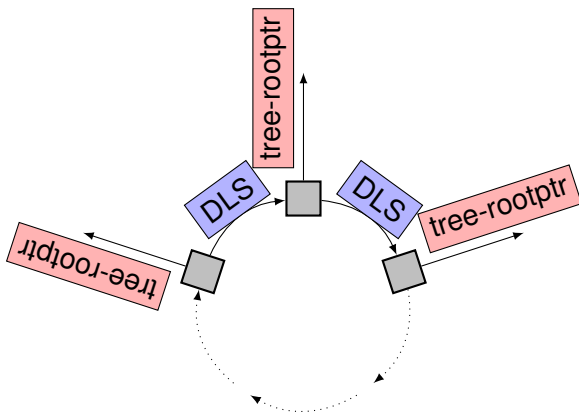
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Learning of Boxes: Example



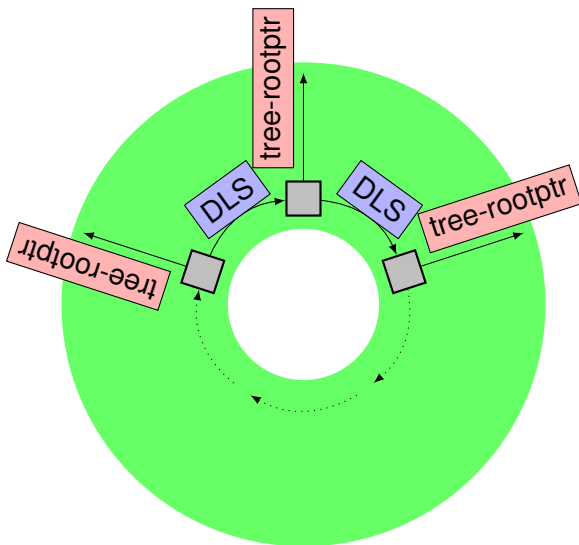
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Learning of Boxes: Example



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Learning of Boxes: Example

circular-DLL-of
-trees-rootptr

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Table : Results of the experiments [s]

Example	FA	Predator	Example	FA	Predator
SLL (delete)	0.04	0.04	DLL (reverse)	0.06	0.03
SLL (bubblesort)	0.04	0.03	DLL (insert)	0.07	0.05
SLL (mergesort)	0.15	0.10	DLL (insertsort ₁)	0.40	0.11
SLL (insertsort)	0.05	0.04	DLL (insertsort ₂)	0.12	0.05
SLL (reverse)	0.03	0.03	DLL of CDLLs	1.25	0.22
SLL+head	0.05	0.03	DLL+subdata	0.09	T
SLL of 0/1 SLLs	0.03	0.11	CDLL	0.03	0.03
SLL _{Linux}	0.03	0.03	tree	0.14	Err
SLL of CSLLs	0.73	0.12	tree+parents	0.21	T
SLL of 2CDLLs _{Linux}	0.17	0.25	tree+stack	0.08	Err
skip list ₂	0.42	T	tree (DSW) ^{Deutsch-Schorr-Waite}	0.40	Err
skip list ₃	9.14	T	tree of CSLLs	0.42	Err

timeout

false positive

Conclusion

Shape analysis with [forest automata](#):

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Shape analysis with **forest automata**:

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- successfully verified:
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Shape analysis with **forest automata**:

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- **Forester** tool
- successfully verified:
 - (singly/doubly linked (circular)) **lists** (of (...) lists)
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 - **skip lists**
- not covered here:
 - support for **pointer arithmetic**
 - tracking **ordering** relations
 - P. Abdulla, L. Holík, B. Jonsson, O. Lengál, C.Q. Tring, and T. Vojnar. **Verification of Heap Manipulating Programs with Ordered Data by Extended Forest Automata**. To appear in *Proc. of ATVA'13*.

Future work

- CEGAR loop
 - **red-black** trees, ...

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- **concurrent** data structures
 - lockless skip lists, ...
- **recursive** boxes
 - B+ trees, ...